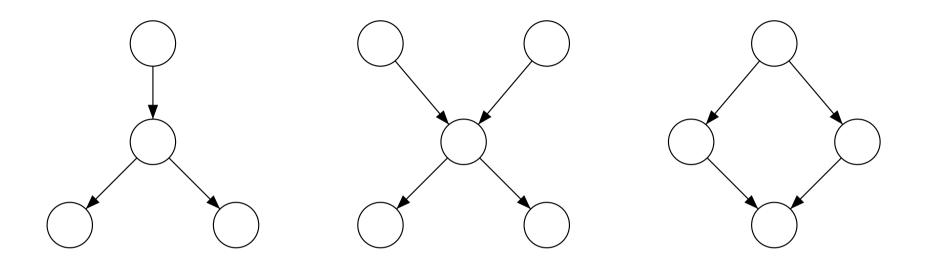
Inference in Bayes-Networks and Markov-Networks

Problems



The propagation algorithm as presented can only deal with *trees*.

Can be extended to *polytrees* (i. e. singly connected graphs with multiple parents per node).

However, it cannot handle networks that contain loops!

Main Objectives:

Transform the cyclic directed graph into a secondary structure without cycles.

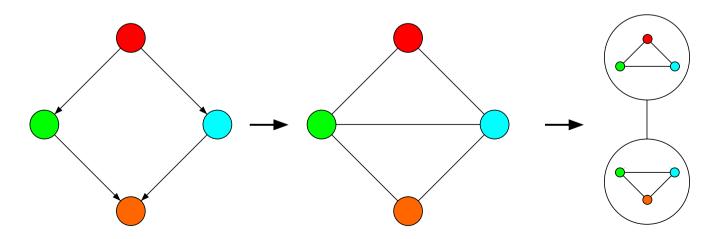
Find a decomposition of the underlying joint distribution.

Task:

Combine nodes of the original (primary) graph structure.

These groups form the nodes of a secondary structure.

Find a transformation that yields tree structure.



Idea (2)

Secondary Structure:

We will generate an undirected graph mimicking (some of) the conditional independence statements of the cyclic directed graph.

Maximal cliques are identified and form the nodes of the secondary structure.

Specify a so-called potential function for every clique such that the product of all potentials yields the initial joint distribution.

In order to propagate evidence, create a **tree** from the clique nodes such that the following property is satisfied:

If two cliques have some attributes in common, then these attributes have to be contained in every clique of the path connecting the two cliques. (called the **running intersection property**, **RIP**)

Justification:

Tree: Unique path of evidence propagation.

RIP: Update of an attribute reaches all cliques which contain it.

Prerequisites

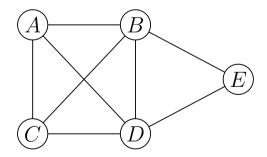
Complete Graph

An undirected Graph G = (V, E) is called *complete*, if every pair of (distinct) nodes is connected by an edge.

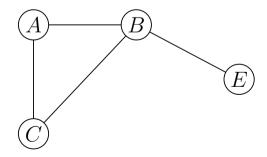
Induced Subgraph

Let G = (V, E) be an undirected graph and $W \subseteq V$ a selection of nodes. Then, $G_W = (W, E_W)$ is called the *subgraph of G induced by W* with E_W being

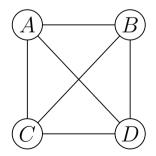
$$E_W = \{(u, v) \in E \mid u, v \in W\}.$$



Incomplete graph



Subgraph (W, E_W) with $W = \{A, B, C, E\}$



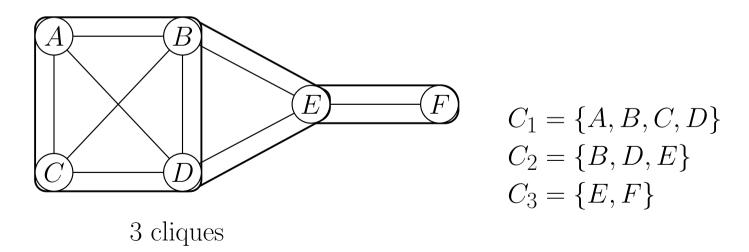
Complete (sub)graph

Prerequisites (2)

Complete Set, Clique

Let G = (V, E) be an undirected graph. A set $W \subseteq V$ is called *complete* iff it induces a complete subgraph. It is further called a *clique*, iff W is maximal, i.e. it is not possible to add a node to W without violating the completeness condition.

- a) W is complete $\Leftrightarrow W$ induces a complete subgraph
- b) W is a clique $\Leftrightarrow W$ is complete and maximal



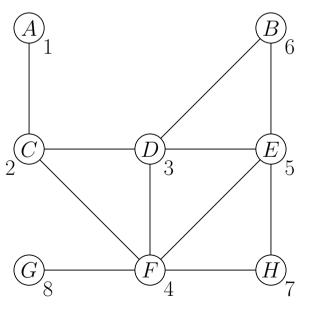
Prerequisites (3)

Perfect Ordering

Let G = (V, E) be an undirected graph with n nodes and $\alpha = \langle v_1, \dots, v_n \rangle$ a total ordering on V. Then, α is called *perfect*, if the following sets

$$adj(v_i) \cap \{v_1, \dots, v_{i-1}\}$$
 $i = 1, \dots, n$

are complete, where $adj(v_i) = \{w \mid (v_i, w) \in E\}$ returns the adjacent nodes of v_i .



$\alpha = \langle A, C$	C, D,	F, E,	B, H	$, G \rangle$
-------------------------	-------	-------	------	---------------

i	$\operatorname{adj}(v_i)$	$\mid \operatorname{adj}(v_i) \cap \{v_1, \dots, v_{i-1}\}$		
1	$\{C\}$	$\{C\} \cap \emptyset$	$=\emptyset$	complete
2	$\{A, D, F\}$	$\{A\} \cap \{A,D,F\}$	$= \{A\}$	complete
3	$\{C, B, E, F\}$	$\{A,C\} \cap \{C,B,E,F\}$	$= \{C\}$	complete
4	$\{G, C, D, E, H\}$	$\{A, C, D\} \cap \{G, C, D, E, H\}$	$= \{C, D\}$	complete
5	$\{B, D, F, H\}$	$\{A, C, D, F\} \cap \{B, D, F, H\}$	$= \{D, F\}$	complete
6	$\{D, E\}$	$\{A, C, D, F, E\} \cap \{D, E\}$	$= \{D, E\}$	complete
7	$\{F, E\}$	$\{A, C, D, F, E, B\} \cap \{F, E\}$	$= \{F, E\}$	complete
8	$\{F\}$	$A, C, D, F, E, B, H \cap \{F\}$	$= \{F\}$	complete

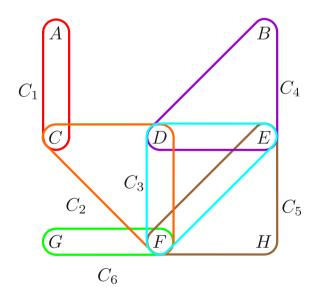
 α is a perfect ordering

Prerequisites (4)

Running Intersection Property

Let G = (V, E) be an undirected graph with p cliques. An ordering of these cliques has the running intersection property (RIP), if for every j > 1 there exists an i < j such that:

$$C_j \cap \left(C_1 \cup \dots \cup C_{j-1}\right) \subseteq C_i$$



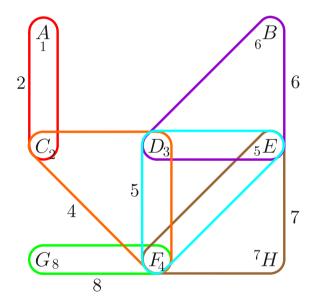
$$\xi = \langle C_1, C_2, C_3, C_4, C_5, C_6 \rangle$$

j				$\mid i \mid$
2	$C_2 \cap C_1$	$=\{C\}$	$\subseteq C_1$	1
3	$C_3 \cap (C_1 \cup C_2)$	$= \{D, F\}$	$\subseteq C_2$	2
4	$C_4 \cap (C_1 \cup C_2 \cup C_3)$	$= \{D, E\}$	$\subseteq C_3$	3
5	$C_5 \cap (C_1 \cup C_2 \cup C_3 \cup C_4)$	$= \{E, F\}$	$\subseteq C_3$	3
6	$C_6 \cap (C_1 \cup C_2 \cup C_3 \cup C_4 \cup C_5)$	$= \{F\}$	$\subseteq C_5$	5

 ξ has running intersection property

Prerequisites (5)

If a node ordering α of an undirected graph G = (V, E) is perfect and the cliques of G are ordered according to the highest rank (w.r.t. α) of the containing nodes, then this clique ordering has RIP.



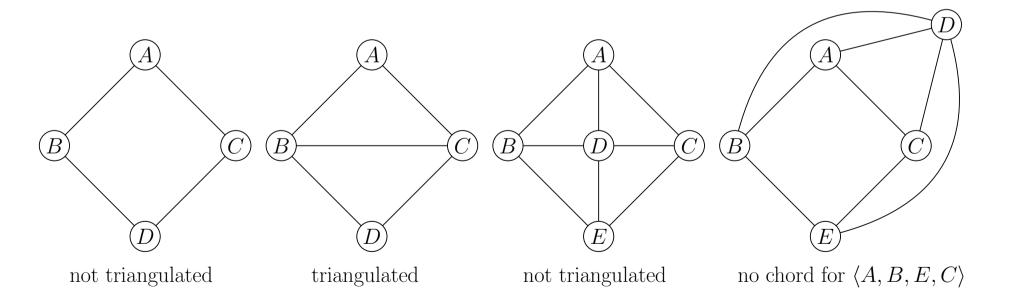
Clique	Rank		
$\overline{\{A,C\}}$	$\max\{\alpha(A), \alpha(C)\}$	=2	$\rightarrow C_1$
$\{C, D, F\}$	$\max\{\alpha(C), \alpha(D), \alpha(F)\}$	=4	$\rightarrow C_2$
$\{D, E, F\}$	$\max\{\alpha(D), \alpha(E), \alpha(F)\}$	=5	$\rightarrow C_3$
$\{B,D,E\}$	$\max\{\alpha(B), \alpha(D), \alpha(E)\}$	= 6	$\rightarrow C_4$
$\{F, E, H\}$	$\max\{\alpha(F), \alpha(E), \alpha(H)\}$	=7	$\rightarrow C_5$
$\{F,G\}$	$\max\{\alpha(F),\alpha(G)\}$	=8	$\rightarrow C_6$

How to get a perfect ordering?

Triangulated Graphs

Triangulated Graph

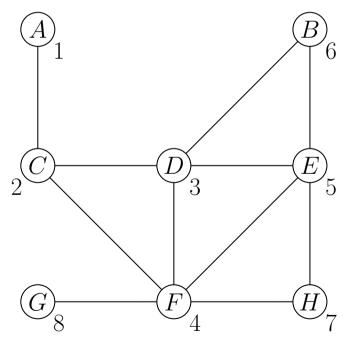
An undirected graph is called *triangulated* if every simple loop (i. e. path with identical start and end node but with any other node occurring at most once) of length greater 3 has a chord.



Triangulated Graphs (2)

Maximum Cardinality Search

Let G = (V, E) be an undirected graph. An ordering according maximum cardinality search (MCS) is obtained by first assigning 1 to an arbitray node. If n numbers are assigned the node that is connected to most of the nodes already numbered gets assigned number n + 1.



3 can be assigned to D or F

6 can be assigned to H or B

Triangulated Graphs (3)

An undirected graph is triangulated iff the ordering obtained by MCS is perfect.

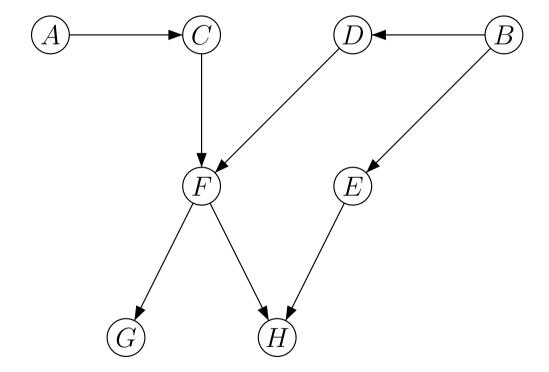
To check whether a graph is triangulated is efficient to implement. The optimization problem that is related to the triangulation task is NP-hard. However, there are good heuristics.

Moral Graph (Repetition)

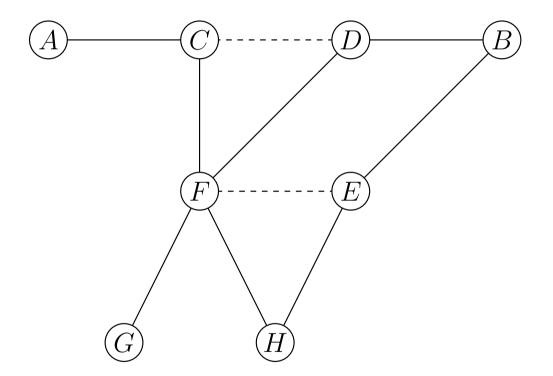
Let G = (V, E) be a directed acyclic graph. If $u, w \in W$ are parents of $v \in V$ connect u and w with an (arbitrarily oriented) edge. After the removal of all edge directions the resulting graph $G_m = (V, E')$ is called the *moral graph* of G.

Join-Tree Construction (1)

Given directed graph.

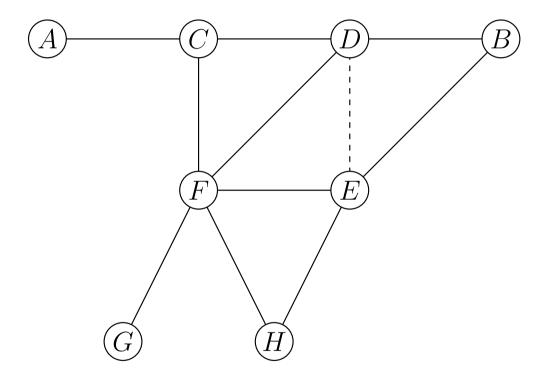


Join-Tree Construction (2)



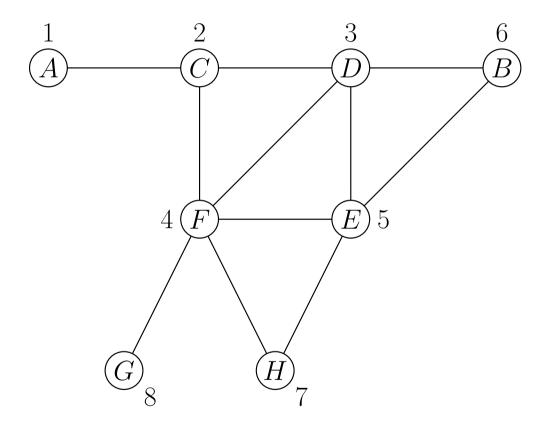
• Moral graph

Join-Tree Construction (3)



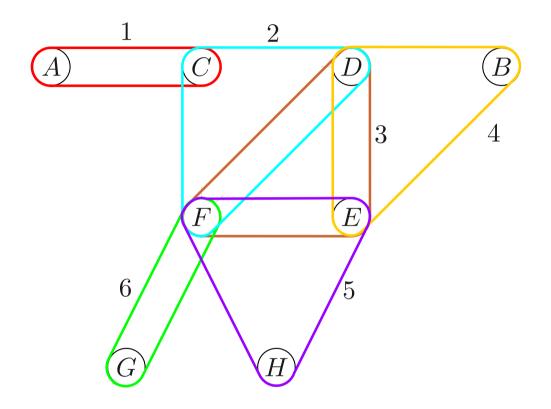
- Moral graph
- Triangulated graph

Join-Tree Construction (4)



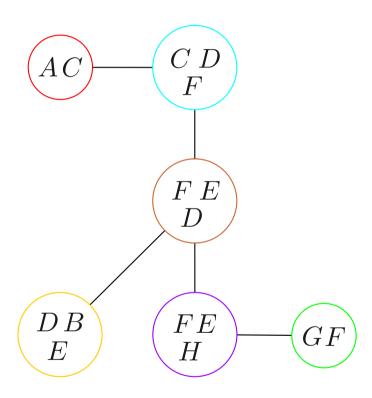
- Moral graph
- Triangulated graph
- MCS yields perfect ordering

Join-Tree Construction (5)



- Moral graph
- Triangulated graph
- MCS yields perfect ordering
- Clique order has RIP

Join-Tree Construction (6)



- Moral graph
- Triangulated graph
- MCS yields perfect ordering
- Clique order has RIP
- Form a join-tree

Two cliques can be connected if they have a non-empty intersection. The generation of the tree follows the RIP. In case of a tie, connect cliques with the largest intersection. (e. g. DBE - FED instead of DBE - CFD) Break remaining ties arbitrarily.

Example: Expert Knowledge

Qualitative knowledge:

Metastatic cancer is a possible cause of brain tumor, and is also an explanation for increased total serum calcium. In turn, either of these could explain a patient falling into a coma. Severe headache is also possibly associated with a brain tumor.

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Special case:

The patient has heavy headache.

Query:

Will the patient fall into coma?

Example: Choice of State Space

Attribute		Possible Values		
A	metastatic cancer	$dom(A) = \{a_1, a_2\}$	$\cdot_1 = \text{existing}$	
$\mid B \mid$	increased total serum calcium	$dom(B) = \{b_1, b_2\}$	$\cdot_2 = \text{notexisting}$	
C	brain tumor	$dom(C) = \{c_1, c_2\}$		
D	coma	$dom(D) = \{d_1, d_2\}$		
$oxed{E}$	severe headache	$dom(E) = \{e_1, e_2\}$		

Exhaustive state space:

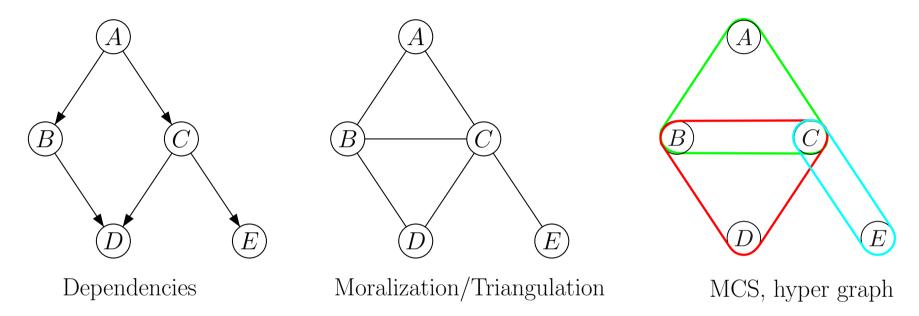
$$\Omega = \mathrm{dom}(A) \times \mathrm{dom}(B) \times \mathrm{dom}(C) \times \mathrm{dom}(D) \times \mathrm{dom}(E)$$

Marginal and conditional probabilities have to be specified!

Example: Qualitative Knowledge

Propagation on Cliques (1)

Example: Metastatic Cancer





Clique tree with separator sets

Propagation on Cliques (3)

Quantitative knowledge:

(a, b, c)	P(a,b,c)	(b, c, d)	P(b, c, d)	(c,e)	P(c,e)
a_1, b_1, c_1	0.032	b_1, c_1, d_1	0.032	c_1, e_1	0.064
a_2, b_1, c_1	0.008	b_2, c_1, d_1	0.032	c_2, e_1	0.552
:	:	:	:	c_1, e_2	0.016
a_2, b_2, c_2	0.608	b_2, c_2, d_2	0.608	c_2, e_2	0.368

Potential representation:

$$\begin{array}{ll} P(A,B,C,D,E,) &=& P(A\mid\emptyset)P(B\mid A)P(C\mid A)P(D\mid BC)P(E\mid C) \\ &=& \frac{P(A,B,C)P(B,C,D),P(C,E)}{P(BC)P(C)} \end{array}$$

Propagation on Cliques (4)

Propagation:

$$P(d_1) = 0.32$$
, evidence $E = e_1$, desired: $P^*(...) = P(\cdot | \{e_1\})$

$$P^*(c) = P(c \mid e_1)$$

conditional marginal distribution

$$P^*(b, c, d) = \frac{P(b, c, d)}{P(c)} P(c \mid e_1)$$
 multipl./division with separation prob.

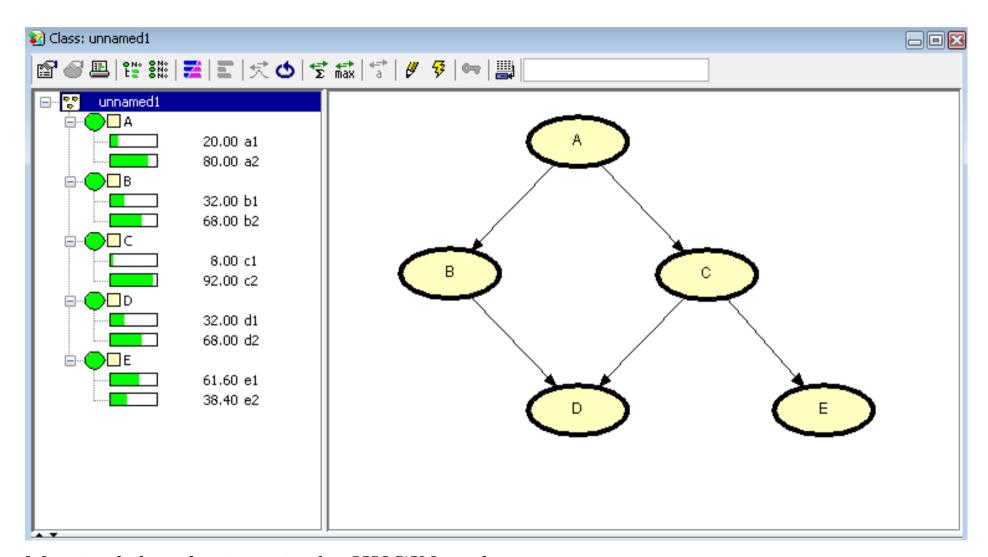
$$P(b,c,d), P^*(b,c)$$

calculate marginal distributions

$$P^*(a, b, c) = \frac{P(a, b, c)}{P(b, c)} P(b, c \mid e_1)$$
 multipl./division with separation prob.

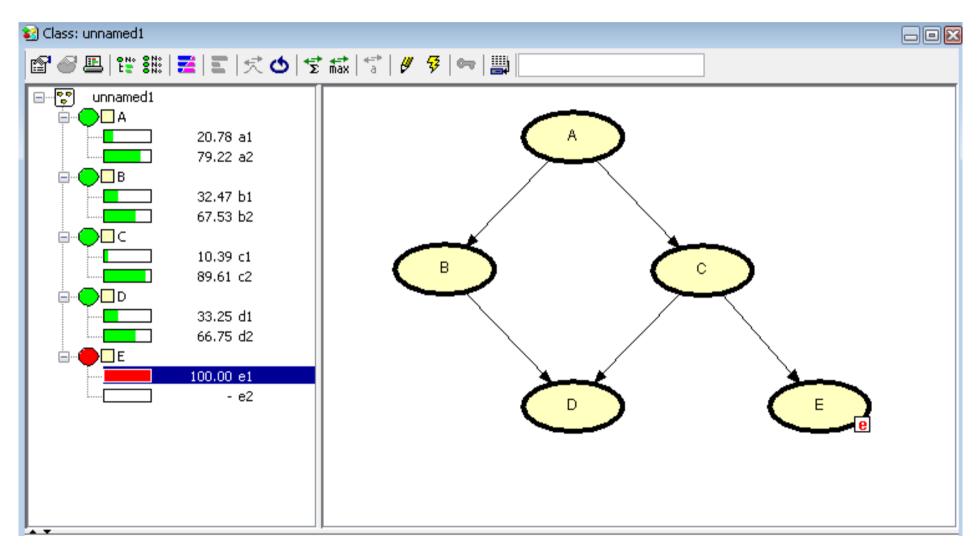
$$P^*(d_1) = P(d_1 \mid e_1) = 0.33$$

Propagation on Cliques (5)



Marginal distributions in the HUGIN tool.

Propagation on Cliques (6)



Conditional marginal distributions with evidence $E = e_1$

Factorization

Potential Representation

Let $V = \{X_j\}$ be a set of random variables $X_j : \Omega \to \text{dom}(X_j)$ and P the joint distribution over V. Further, let

$$\{W_i \mid W_i \subseteq V, 1 \le i \le p\}$$

a family of subsets of V with associated functions

$$\psi_i: \underset{X_j \in W_i}{\times} \operatorname{dom}(X_j) \to \mathbb{R}$$

It is said that P(V) factorizes according $(\{W_1, \ldots, W_p\}, \{\psi_1, \ldots, \psi_p\})$ if P(V) can be written as:

$$P(v) = k \cdot \prod_{i=1}^{p} \psi_i(w_i)$$

where $k \in \mathbb{R}$, w_i is a realization of W_i that meets the values of v.

Example

$$(A) \qquad (B) \qquad (C)$$

$$V = \{A, B, C\}, W_1 = \{A, B\}, W_2 = \{B, C\}$$

$$dom(A) = \{a_1, a_2\}$$

$$dom(B) = \{b_1, b_2\}$$

$$dom(C) = \{c_1, c_2\}$$

$$P(a,b,c) = \frac{1}{8}$$

$$\psi_1 : \{a_1, a_2\} \times \{b_1, b_2\} \to \mathbb{R}$$

 $\psi_2 : \{b_1, b_2\} \times \{c_1, c_2\} \to \mathbb{R}$

$$\psi_1(a,b) = \frac{1}{4}$$

 $\psi_2(b,c) = \frac{1}{2}$

 $(\{W_1, W_2\}, \{\psi_1, \psi_2\})$ is a potential representation of P.

Factorization of a Belief Network

Let (V, E, P) be an belief network and $\{C_1, \ldots, C_p\}$ the cliques of the join tree. For every node $v \in V$ choose a clique C such that v and all of its parents are contained in C, i. e. $\{v\} \cup c(v) \subseteq C$. The chosen clique is designated as f(v).

To arrive at a factorization $(\{C_1, \ldots, C_p\}, \{\psi_1, \ldots, \psi_p\})$ of P the factor potentials are:

$$\psi_i(c_i) = \prod_{v: f(v) = C_i} P(v \mid c(v))$$

Separator Sets and Residual Sets

Let $\{C_1, \ldots, C_p\}$ be a set of cliques w.r.t. V. The sets

$$S_i = C_i \cap (C_1 \cup \cdots \cup C_{i-1}), \qquad i = 1, \ldots, p, \qquad S_1 = \emptyset$$

are called *separator sets* with their corresponding *residual sets*

$$R_i = C_i \backslash S_i$$

Decomposition w.r.t. a Join-Tree

Given a clique ordering $\{C_1, \ldots, C_p\}$ that satisfies the RIP, we can easily conclude the following separation statements:

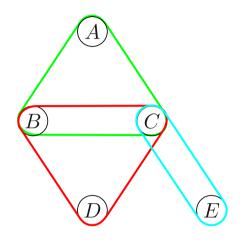
$$R_i \perp \!\!\!\perp (C_1 \cup \cdots \cup C_{i-1}) \backslash S_i \mid S_i \quad \text{for } i > 1$$

Hence, we can formulate the following factorization:

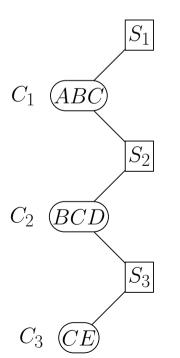
$$P(X_1, \dots, X_n) = \prod_{i=1}^{p} P(R_i \mid S_i),$$

which also gives us a representation in terms of conditional probabilities (as for directed graphs before).

Example



$$S_1 = \emptyset$$
 $R_1 = \{A, B, C\}$ $f(A) = C_1$
 $S_2 = \{B, C\}$ $R_2 = \{D\}$ $f(B) = C_1$
 $S_3 = \{C\}$ $R_3 = \{E\}$ $f(C) = C_1$
 $f(E) = C_2$



$$\psi_1(C_1) = P(A, B, C \mid \emptyset) = P(A) \cdot P(C \mid A) \cdot P(B \mid A)$$

$$\psi_2(C_2) = P(D \mid B, C)$$

$$\psi_3(C_3) = P(E \mid C)$$

Propagation is accomplished by sending messages across the cliques in the tree. The emerging potentials are maintained by each clique.

Propagation in Join Trees

Main Idea

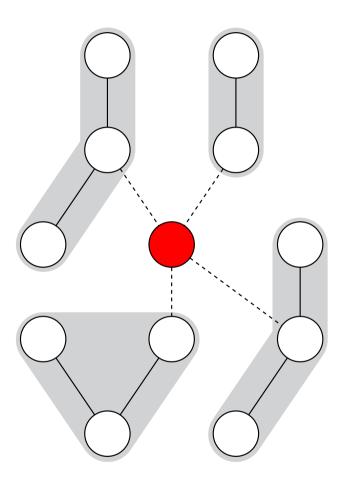
Incorporate evidence into the clique potentials.

Since we are dealing with a tree structure, exploit the fact that a clique "separates" all its neighboring cliques (and their respective subtrees) from each other.

Apply a message passing scheme to inform neighboring cliques about evidence.

Since we do not have edge directions, we will only need one type of message.

After having updated all cliques' potentials, we marginalize (and normalize) to get the probabilities of single attributes.



Incorporating Evidence

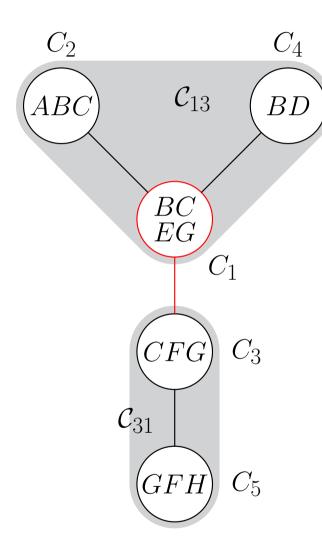
Every clique C_i maintains a potential function ψ_i .

If for an attribute E some evidence e becomes known, we alter all potential functions of cliques containing E as follows:

$$\psi_i^*(c_i) = \begin{cases} 0, & \text{if a value in } c_i \text{ is inconsistent with } e \\ \psi_i(c_i), & \text{otherwise} \end{cases}$$

All other potential functions are unchanged.

Notation and Nomenclature



In general:

Clique C_i has q neighboring cliques B_1, \ldots, B_q .

 C_{ij} is the set of cliques in the subtree containing C_i after dropping the link to B_i .

 X_{ij} is the set of attributes in the cliques of C_{ij} .

$$V = X_{ij} \cup X_{ji}$$
 (complementary sets)

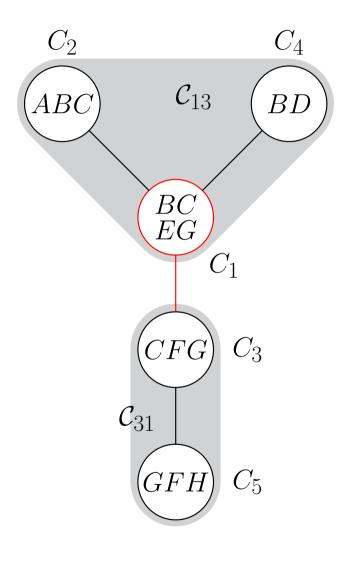
$$S_{ij} = S_{ji} = C_i \cap C_j$$
 (not shown here)

$$R_{ij} = X_{ij} \setminus S_{ij}$$
 (not shown here)

Here:

Neighbors of C_1 : $\{C_2, C_4, C_3\}, C_{13} = \{C_1, C_2, C_4\}$ $X_{13} = \{A, B, C, D, E, G\}, S_{13} = \{C, G\}$ $V = X_{13} \cup X_{31} = \{A, B, C, D, E, F, G, H\}$ $R_{13} = \{A, B, D, E\}, R_{31} = \{F, H\}$

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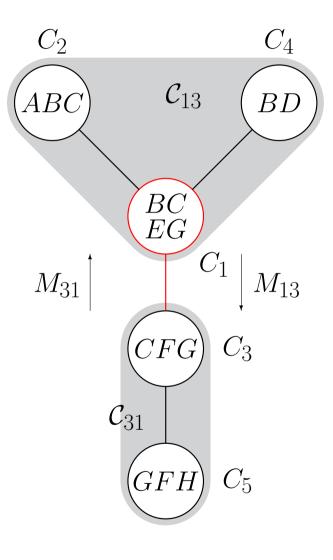
Task: Calculate $P(s_{ij})$:

$$V \setminus S_{ij} = (X_{ij} \cup X_{ji}) \setminus S_{ij}$$
$$= (X_{ij} \setminus S_{ij}) \cup (X_{ji} \setminus S_{ij})$$
$$= R_{ij} \cup R_{ji}$$

$$V \setminus S_{13} = (X_{13} \cup X_{31}) \setminus S_{13}$$

= $R_{13} \cup R_{31}$
 $V \setminus \{C, G\} = \{A, B, D, E\} \cup \{F, H\}$
= $\{A, B, D, E, F, H\}$

Note: R_{ij} is the set of attributes that are in C_i 's subtree but not in B_j 's. Therefore, R_{ij} and R_{ji} are always **disjoint**.



Task: Calculate $P(s_{ij})$:

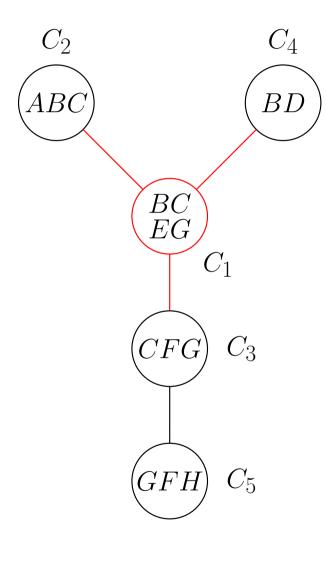
$$P(s_{ij}) = \sum_{v \setminus s_{ij}} \prod_{k=1}^{m} \psi_k(c_k)$$

$$\stackrel{\text{last slide}}{=} \sum_{r_{ij} \cup r_{ji}} \prod_{k=1}^{m} \psi_k(c_k)$$

$$\stackrel{\text{sum rule}}{=} \left(\sum_{r_{ij}} \prod_{c_k \in \mathcal{C}_{ij}} \psi_k(c_k) \right) \cdot \left(\sum_{r_{ji}} \prod_{c_k \in \mathcal{C}_{ji}} \psi_k(c_k) \right)$$

$$= M_{ij}(s_{ij}) \cdot M_{ji}(s_{ij})$$

 M_{ij} is the message sent from C_i to neighbor B_j and vice versa.



Task: Calculate $P(c_i)$:

$$V \setminus C_i = \left(\bigcup_{k=1}^q X_{ki}\right) \setminus C_i$$

$$= \bigcup_{k=1}^q \left(X_{ki} \setminus C_i\right)$$

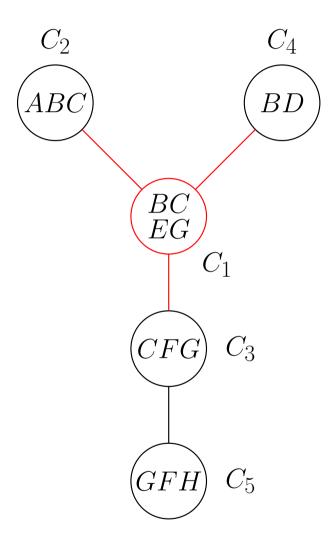
$$= \bigcup_{k=1}^q R_{ki}$$

$$= \bigcup_{k=1}^q R_{ki}$$

Example:

$$V \setminus C_1 = R_{21} \cup R_{41} \cup R_{31}$$

 $\{A, D, F, H\} = \{A\} \cup \{D\} \cup \{F, H\}$



Task: Calculate $P(c_i)$:

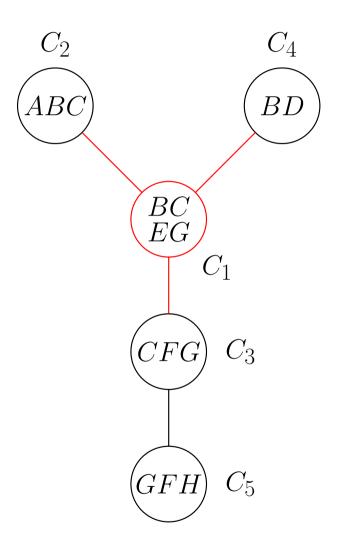
$$P(c_{i}) = \sum_{\substack{v \setminus c_{i} \\ \text{Marginalization Decomposition}}} \prod_{j=1}^{m} \psi_{j}(c_{j})$$

$$= \psi_{i}(c_{i}) \sum_{\substack{v \setminus c_{i} \\ i \neq j}} \prod_{j \neq j} \psi_{j}(c_{j})$$

$$= \psi_{i}(c_{i}) \sum_{\substack{r_{1i} \cup \cdots \cup r_{qi} \\ i \neq j}} \prod_{i \neq j} \psi_{j}(c_{j})$$

$$= \psi_{i}(c_{i}) \left(\sum_{\substack{r_{1i} \\ C_{k} \in \mathcal{C}_{1i} \\ M_{1i}(s_{ij})}} \psi_{k}(c_{k}) \right) \cdots \left(\sum_{\substack{r_{qi} \\ C_{k} \in \mathcal{C}_{qi} \\ M_{qi}(s_{ij})}} \psi_{k}(c_{k}) \right)$$

$$= \psi_{i}(c_{i}) \prod_{j=1}^{q} M_{ji}(s_{ij})$$



Example: $P(c_1)$:

$$P(c_1) = \psi_1(c_1)M_{21}(s_{12})M_{41}(s_{14})M_{31}(s_{13})$$

 $M_{ij}(s_{ij})$ can be simplified further (without proof):

$$M_{ij}(s_{ij}) = \sum_{r_{ij}} \prod_{c_k \in \mathcal{C}_{ij}} \psi_k(c_k)$$
$$= \sum_{c_i \setminus s_{ij}} \psi_i(c_i) \prod_{k \neq j} M_{ki}(s_{ki})$$

Final Algorithm

Input: Join tree (\mathcal{C}, Ψ) over set of variables V and evidence E = e.

Output: The a-posteriori probability $P(x_i | e)$ for every non-evidential X_i .

Initialization: Incorporate evidence E = e into potential functions.

Iterations:

- 1. For every clique C_i do: For every neighbor B_j of C_i do: If C_i has received all messages from the *other* neighbors, calculate and send $M_{ij}(s_{ij})$ to B_j .
- 2. Repeat step 1 until no message is calculated.
- 3. Calculate the joint probability distribution for every clique:

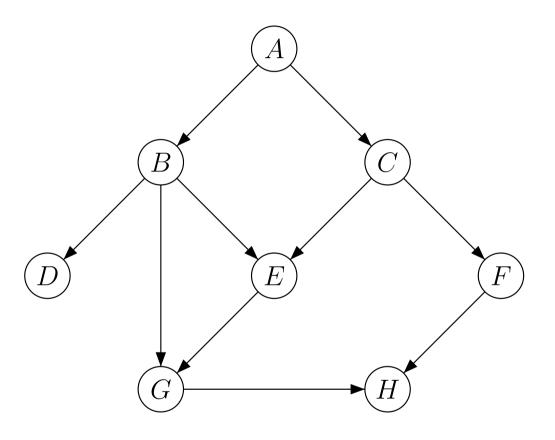
$$P(c_i) \propto \psi_i(c_i) \prod_{j=1}^q M_{ji}(s_{ij})$$

4. For every $X \in V$ calculate the a-posteriori probability:

$$P(x_i \mid e) = \sum_{c_k \setminus x_i} P(c_k)$$

where C_k is the smallest clique containing X_i .

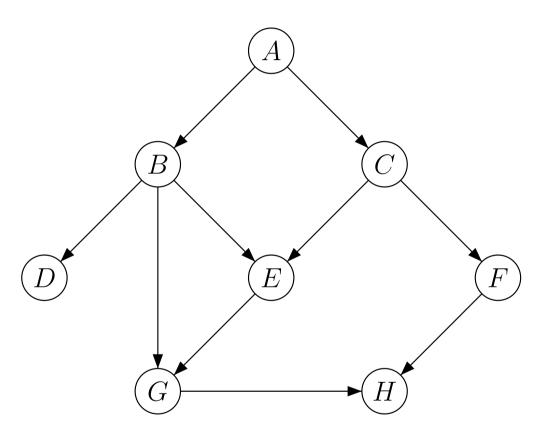
Example: Putting it together

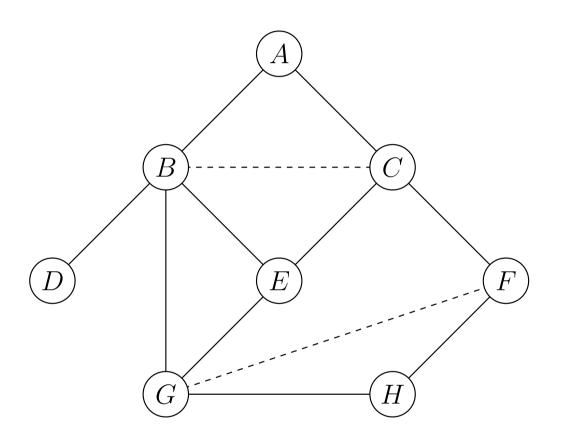


Goals: Find the marginal distributions and update them when evidence $H = h_1$ becomes known.

Steps:

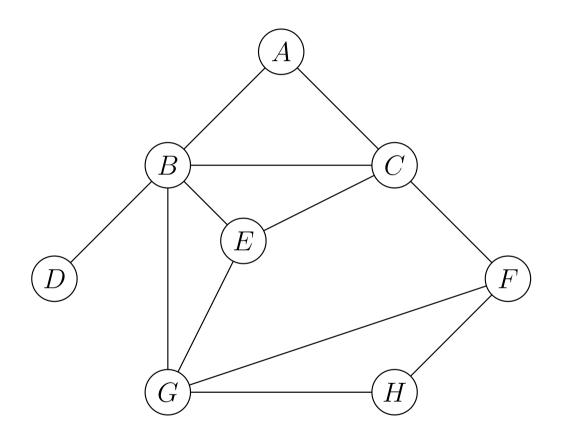
- 1. Transform network into join-tree.
- 2. Specify factor potentials.
- 3. Propagate "zero" evidence to obtain the marginals before evidence is present.
- 4. Update factor potentials w.r.t. the evidence and do another propagation run.



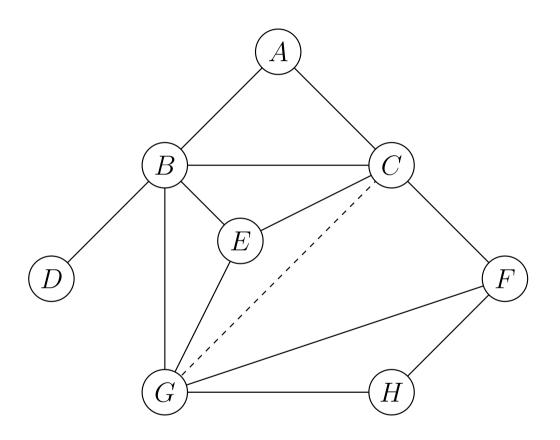


Join-Tree creation:

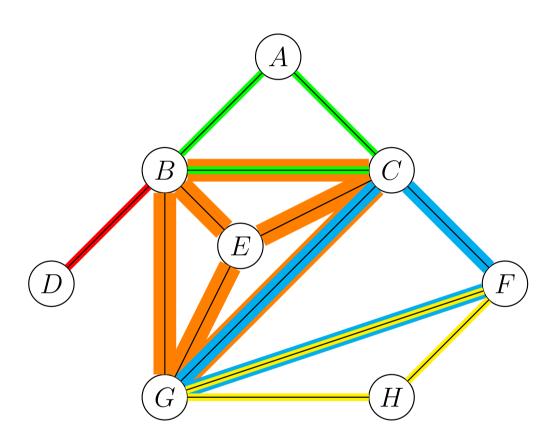
1. Moralize the graph.



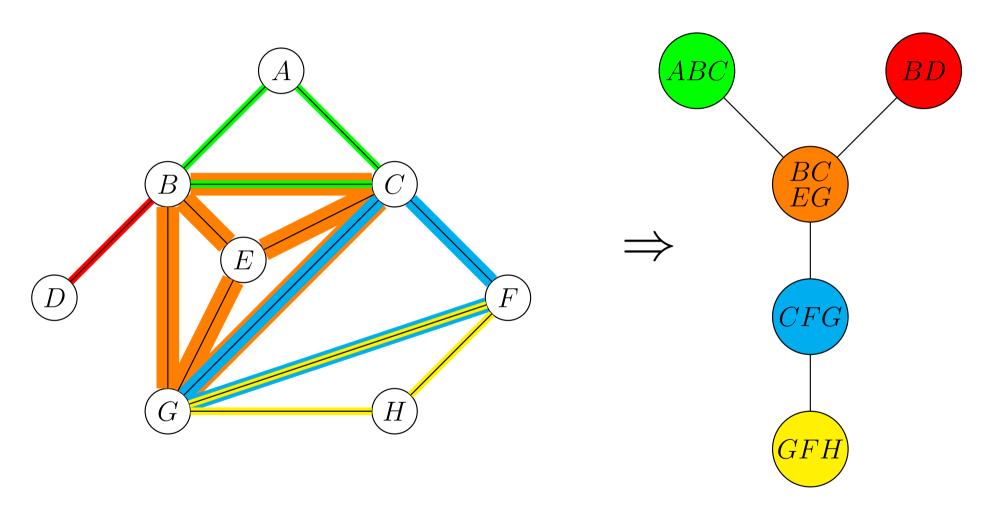
- 1. Moralize the graph.
- 2. Not yet triangulated.



- 1. Moralize the graph.
- 2. Triangulate the graph.



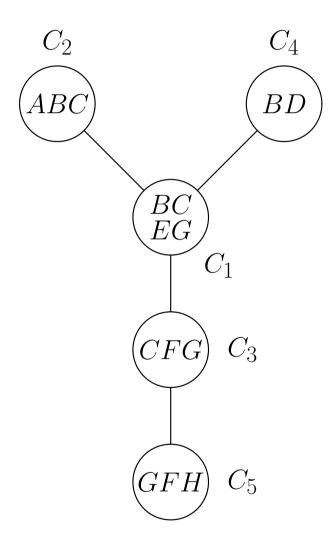
- 1. Moralize the graph.
- 2. Triangulate the graph.
- 3. Identify the maximal cliques.



Example Bayesian network

One of the join trees

Example: Step 2: Specify the Factor Potentials



Decomposition of P(A, B, C, D, E, F, G, H):

$$P(a, b, c, d, e, f, g, h) = \prod_{i=1}^{5} \Psi_{i}(c_{i})$$

$$= \Psi_{1}(b, c, e, g) \cdot \Psi_{2}(a, b, c)$$

$$\cdot \Psi_{3}(c, f, g) \cdot \Psi_{4}(b, d)$$

$$\cdot \Psi_{5}(g, f, h)$$

Where to get the factor potentials from?

Example: Step 2: Specify the Factor Potentials

As long as the factor potentials multiply together as on the previous slide, we are free to choose them.

Option 1: A factor potential of clique C_i is the product of all conditional probabilities of all node families properly contained in C_i :

$$\Psi_i(c_i) = 1 \cdot \prod_{\substack{\{X_i\} \cup Y_i \subseteq C_i \land \\ \text{parents}(X_i) = Y_i}} P(x_i \mid y_i)$$

The 1 stresses that if no node family satisfies the product condition, we assign a constant 1 to the potential.

Option 2: Choose potentials from the decomposition formula:

$$P(\bigcup_{i=1}^{n} C_i) = \frac{\prod_{i=1}^{n} P(C_i)}{\prod_{j=1}^{m} P(S_j)}$$

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Example: Step 2: Specify the Factor Potentials

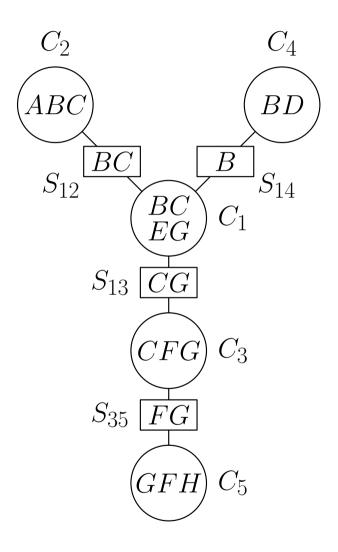
Option 1: Factor potentials according to the conditional distributions of the node families of the underlying Bayesian network:

$$\Psi_{1}(b, c, e, g) = P(e \mid b, c) \cdot P(g \mid e, b)
\Psi_{2}(a, b, c) = P(b \mid a) \cdot P(c \mid a) \cdot P(a)
\Psi_{3}(c, f, g) = P(f \mid c)
\Psi_{4}(b, d) = P(d \mid b)
\Psi_{5}(g, f, h) = P(h \mid g, f)$$

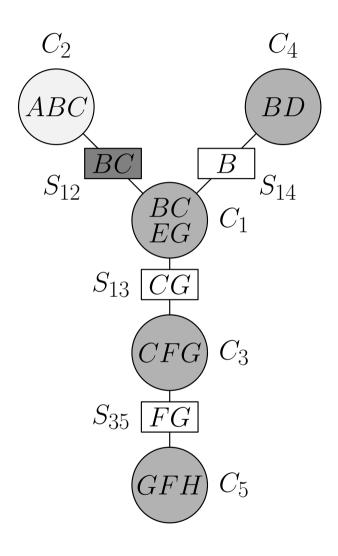
(This assignment of factor potentials is used in this example.)

Option 2: Factor potentials chosen from the join-tree decomposition:

$$\Psi_{1}(b, c, e, g) = P(b, e \mid c, g)
\Psi_{2}(a, b, c) = P(a \mid b, c)
\Psi_{3}(c, f, g) = P(c \mid f, g)
\Psi_{4}(b, d) = P(d \mid b)
\Psi_{5}(g, f, h) = P(h, g, f)$$



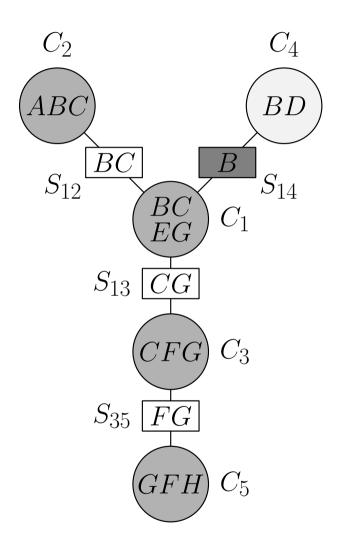
Encoded independence statements:



Encoded independence statements:

Given any separator, the variables in the cliques on one side become independent of the variables in the cliques on the other side.

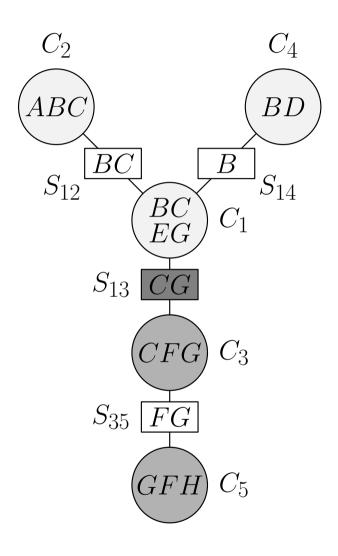
 $A \perp \!\!\!\perp D, E, F, G, H \mid B, C$



Encoded independence statements:

$$A \perp \!\!\!\perp D, E, F, G, H \mid B, C$$

 $D \perp \!\!\!\perp A, C, E, F, G, H \mid B$

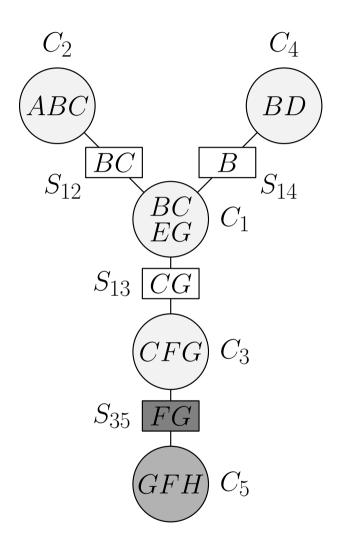


Encoded independence statements:

$$A \perp\!\!\!\perp D, E, F, G, H \mid B, C$$

$$D \perp\!\!\!\!\perp A, C, E, F, G, H \mid B$$

$$A, B, E, D \perp\!\!\!\!\perp F, H \mid G, C$$



Encoded independence statements:

$$A \perp\!\!\!\perp D, E, F, G, H \mid B, C$$

$$D \perp\!\!\!\!\perp A, C, E, F, G, H \mid B$$

$$A, B, E, D \perp\!\!\!\!\perp F, H \mid G, C$$

$$H \perp\!\!\!\!\perp A, B, C, D, E \mid F, G$$

Example: Closer Look on Option 2: Decomposition

The four separation statements translate into the following independence statements:

According to the chain rule we always have the following relation:

$$P(A, B, C, D, E, F, G, H) = P(A \mid B, C, D, E, F, G, H) \cdot P(D \mid B, C, E, F, G, H) \cdot P(B, E \mid C, F, G, H) \cdot P(C \mid F, G, H) \cdot P(F, G, H)$$

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Example: Closer Look on Option 2: Decomposition

The four separation statements translate into the following independence statements:

Exploiting the above independencies yields:

$$P(A, B, C, D, E, F, G, H) = P(A \mid B, C) \cdot P(D \mid B) \cdot P(B, E \mid C, G) \cdot P(C \mid F, G) \cdot P(F, G, H)$$

Example: Closer Look on Option 2: Decomposition

The four separation statements translate into the following independence statements:

$$A \perp\!\!\!\perp D, E, F, G, H \mid B, C \Leftrightarrow P(A \mid B, C, D, E, F, G, H) = P(A \mid B, C)$$

$$D \perp\!\!\!\perp A, C, E, F, G, H \mid B \Rightarrow P(D \mid B, C, E, F, G, H) = P(D \mid B)$$

$$A, B, E, D \perp\!\!\!\!\perp F, H \mid G, C \Rightarrow P(B, E \mid G, C, F, H) = P(B, E \mid G, C)$$

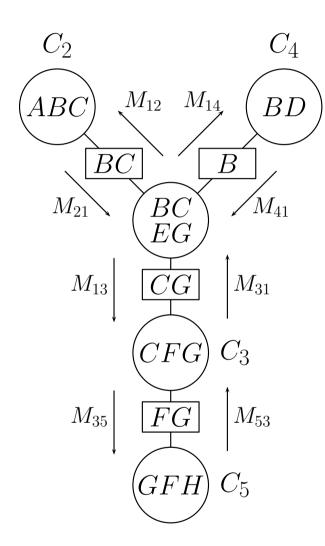
$$H \perp\!\!\!\!\perp A, B, C, D, E \mid F, G \Rightarrow P(C \mid F, G, H) = P(C \mid F, G)$$

Getting rid of the conditions results in the final decomposition equation:

$$\begin{split} P(A,B,C,D,E,F,G,H) &= P(A\,|\,B,C)P(D\,|\,B)P(B,E\,|\,C,G)P(C\,|\,F,G)P(F,G,H) \\ &= \frac{P(A,B,C)P(D,B)P(B,E,C,G)P(C,F,G)P(F,G,H)}{P(B,C)P(B)P(C,G)P(F,G)} \\ &= \frac{P(C_1)P(C_2)P(C_3)P(C_4)P(C_5)}{P(S_{12})P(S_{14})P(S_{13})P(S_{35})} \end{split}$$

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Example: Step 3: Messages to be sent for Propagation



According to the join-tree propagation algorithm, the probability distributions of all clique instantiations c_i is calculated as follows:

$$P(c_i) \propto \Psi_i(c_i) \prod_{j=1}^q M_{ji}(s_{ij})$$

Spelt out for our example, we get:

$$P(c_{1}) = P(b, c, e, g) = \Psi_{1}(b, c, e, g) \cdot M_{21}(b, c) \cdot M_{31}(c, g) \cdot M_{41}(b)$$

$$P(c_{2}) = P(a, b, c) \propto \Psi_{2}(a, b, c) \cdot M_{12}(b, c)$$

$$P(c_{3}) = P(c, f, g) \propto \Psi_{3}(c, f, g) \cdot M_{13}(c, g) \cdot M_{53}(f, g)$$

$$P(c_{4}) = P(b, d) \propto \Psi_{4}(b, d) \cdot M_{14}(b)$$

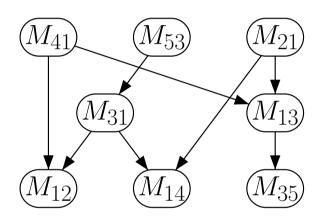
$$P(c_{5}) = P(f, g, h) \propto \Psi_{5}(f, g, h) \cdot M_{35}(f, g)$$

The ∞ -symbol indicates that the right-hand side may not add up to one. In that case we just normalize.

Example: Step 3: Message Computation Order

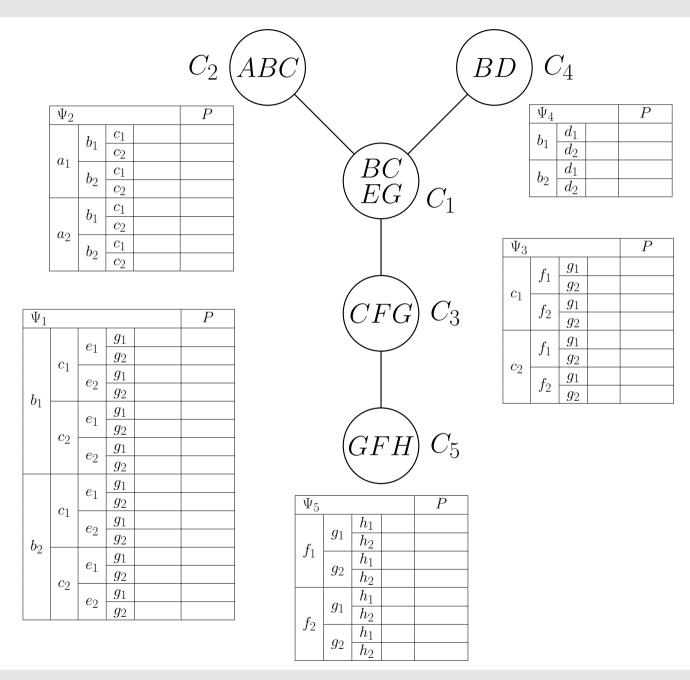
The structure of the join-tree imposes a partial ordering according to which the messages need to be computed:

$$\begin{split} M_{41}(b) &= \sum_{d} \Psi_4(b,d) \\ M_{53}(f,g) &= \sum_{h} \Psi_5(f,g,h) \\ M_{21}(b,c) &= \sum_{a} \Psi_2(a,b,c) \\ M_{31}(c,g) &= \sum_{f} \Psi_3(c,f,g) M_{53}(f,g) \\ M_{13}(c,g) &= \sum_{b,e} \Psi_1(b,c,e,g) M_{21}(b,c) M_{41}(b) \\ M_{12}(b,c) &= \sum_{e,g} \Psi_2(b,c,e,g) M_{31}(c,g) M_{41}(b) \\ M_{14}(b) &= \sum_{c,e,g} \Psi_1(b,c,e,g) M_{21}(b,c) M_{31}(c,g) \\ M_{35}(f,g) &= \sum_{c} \Psi_3(c,f,g) M_{13}(c,g) \end{split}$$

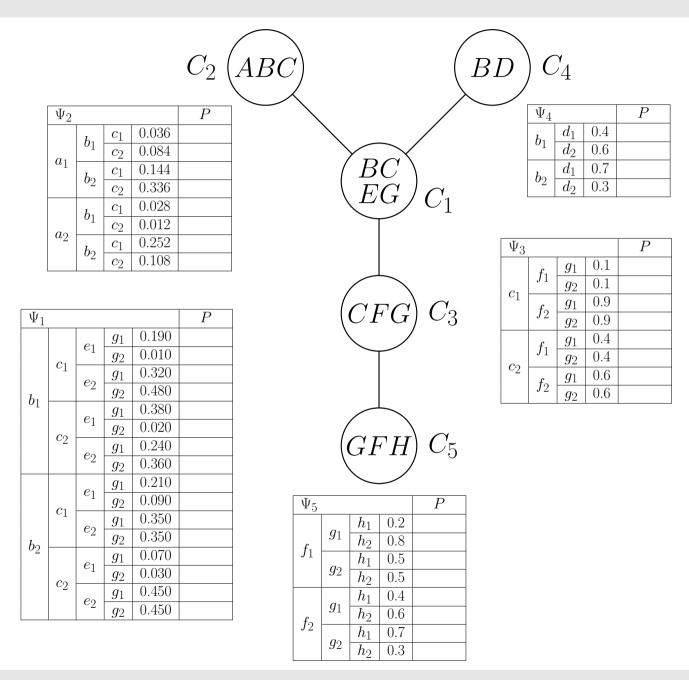


Arrows represent is-needed-for relations. Messages on the same level can be computed in any order. Messages are computed levelwise from top to bottom.

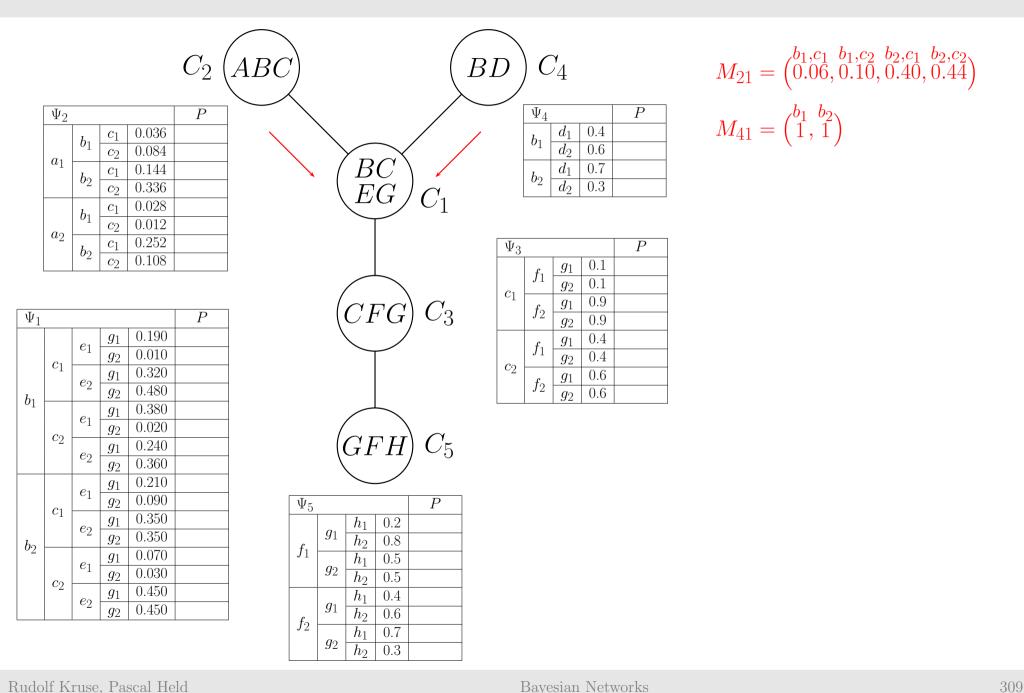
Example: Step 3: Initialization (Potential Layouts)

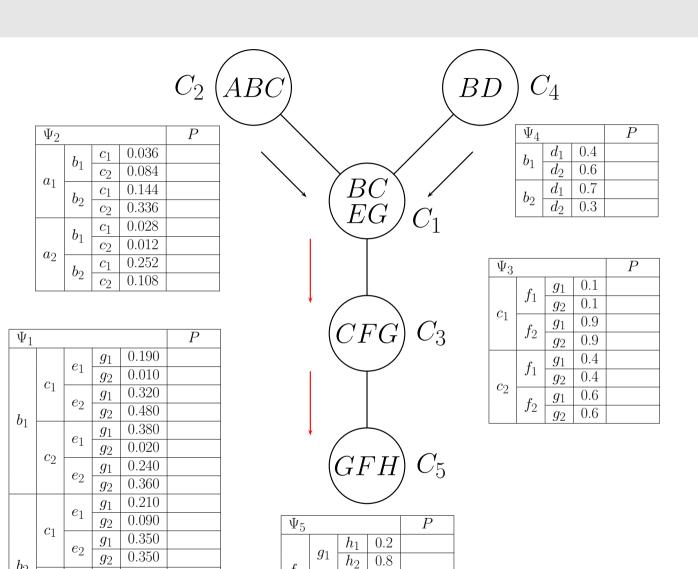


Example: Step 3: Initialization (Potential Values)



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0.5

0.5

0.4

0.6 0.7 0.3

 h_2

 h_1

 h_2

$M_{21} = \begin{pmatrix} b_1, c_1 & b_1, c_2 & b_2, c_1 & b_2, c_2 \\ 0.06, 0.10, 0.40, 0.44 \end{pmatrix}$
$M_{41} = \begin{pmatrix} b_1 & b_2 \\ 1 & 1 \end{pmatrix}$
$M_{13} = \begin{pmatrix} c_{1}, g_{1} & c_{1}, g_{2} & c_{2}, g_{1} & c_{2}, g_{2} \\ 0.254, 0.206, 0.290, 0.250 \end{pmatrix}$
$M_{35} = \begin{pmatrix} f_{1}, g_{1}, f_{1}, g_{2}, f_{2}, g_{1}, f_{2}, g_{2} \\ 0.14, 0.12, 0.40, 0.33 \end{pmatrix}$

0.070

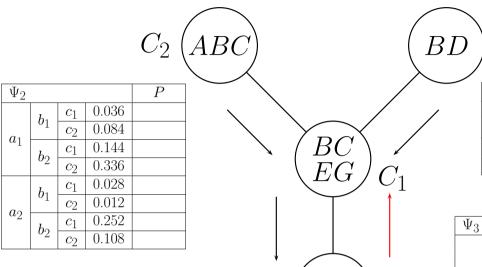
0.030

0.450

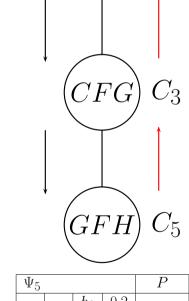
0.450

 g_1

 e_1



Ψ_1					\overline{P}
		0.4	g_1	0.190	
	C1	e_1	g_2	0.010	
	c_1	e_2	g_1	0.320	
b_1		C2	g_2	0.480	
01		$ e_1 $	g_1	0.380	
	c_2		g_2	0.020	
		$ e_2 $	g_1	0.240	
		02	g_2	0.360	
		$ e_1 $	g_1	0.210	
	c_1		g_2	0.090	
		e_2	g_1	0.350	
b_2		02	g_2	0.350	
		$ e_1 $	g_1	0.070	
	c_2		g_2	0.030	
		e_2	g_1	0.450	
			g_2	0.450	



Ψ_5				P
	a.	h_1	0.2	
f_1	g_1	h_2	0.8	
$\int \int 1$	a _o	h_1	0.5	
	g_2	h_2	0.5	
	a.	h_1	0.4	
f_{α}	g_1	h_2	0.6	
f_2	a.	h_1	0.7	
	g_2	h_2	0.3	

Ψ_4			P
b_1	d_1	0.4	
o_1	d_1 d_2	0.6	
h.	d_1 d_2	0.7	
b_2	d_2	0.3	

JIt -				Р
Ψ_3				Γ
	f_1	g_1	0.1	
Ca	J1	g_2	0.1	
c_1	f_2	g_1	0.9	
	J2	g_2	0.9	
	f_1	g_1	0.4	
Co	J1	g_2	0.4	
c_2	f_2	g_1	0.6	
		g_2	0.6	

$$M_{21} = \begin{pmatrix} b_1, c_1 & b_1, c_2 & b_2, c_1 & b_2, c_2 \\ 0.06, 0.10, 0.40, 0.44 \end{pmatrix}$$

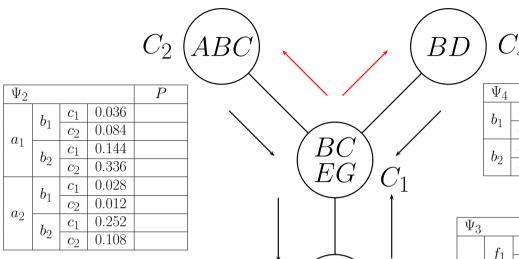
$$M_{41} = \begin{pmatrix} b_1 & b_2 \\ 1, & 1 \end{pmatrix}$$

$$M_{13} = \begin{pmatrix} c_1, g_1 & c_1, g_2 & c_2, g_1 & c_2, g_2 \\ 0.254, 0.206, 0.290, 0.250 \end{pmatrix}$$

$$M_{35} = \begin{pmatrix} f_1, g_1 & f_1, g_2 & f_2, g_1 & f_2, g_2 \\ 0.14, & 0.12, & 0.40, & 0.33 \end{pmatrix}$$

$$M_{53} = \begin{pmatrix} f_1, g_1 & f_1, g_2 & f_2, g_1 & f_2, g_2 \\ 0.14, & 0.12, & 0.40, & 0.33 \end{pmatrix}$$

 $M_{31} = \begin{pmatrix} c_1, g_1 & c_1, g_2 & c_2, g_1 & c_2, g_2 \\ 1 & 1 & 1 & 1 \end{pmatrix}$



νΤι					Р
Ψ_1					P
		$ e_1 $	g_1	0.190	
	Cı		g_2	0.010	
	c_1	00	g_1	0.320	
b_1		e_2	g_2	0.480	
o_1		0.1	g_1	0.380	
	Co	e_1	g_2	0.020	
	c_2	00	g_1	0.240	
		e_2	g_2	0.360	
		0.1	g_1	0.210	
	0.1	e_1	g_2	0.090	
	c_1	00	g_1	0.350	
b_2		e_2	g_2	0.350	
02		0.1	g_1	0.070	
	Co	e_1	g_2	0.030	
	c_2	60	g_1	0.450	
		$\mid e_2 \mid$	g_2	0.450	

	(CFG)	C_3
		1
	(GFH)	C_5
Ψ_5		\overline{P}

	Ψ_5		P		
		Q4	h_1	0.2	
	f_1	g_1	h_2	0.8	
	J1	no.	h_1	0.5	
		g_2	h_2	0.5	
		<i>Q</i> 1	h_1	0.4	
	f_2	g_1	h_2	0.6	
	J2	- A-	h_1	0.7	
		g_2	h_2	0.3	

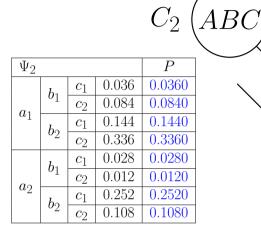
Ψ_4			P
b_1	d_1	0.4	
	d_2	0.6	
b_2	d_1	0.7	
02	d_2	0.3	

Ψ_3				P
	f_1	g_1	0.1	
Ca	J1	g_2	0.1	
c_1	f_2	g_1	0.9	
	J2	g_2	0.9	
	f_1	g_1	0.4	
$ c_2 $	J1	g_2	0.4	
62	f_2	g_1	0.6	
	J2	g_2	0.6	

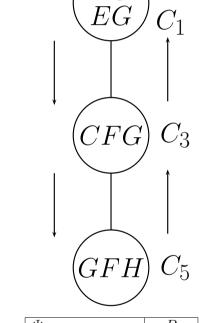
$M_{21} = \begin{pmatrix} b_1, c_1 & b_1, c_2 & b_2, c_1 & b_2, c_2 \\ 0.06, & 0.10, & 0.40, & 0.44 \end{pmatrix}$
$M_{41} = \begin{pmatrix} b_1 & b_2 \\ 1 & 1 \end{pmatrix}$
$M_{13} = \begin{pmatrix} c_{1}, g_{1} & c_{1}, g_{2} & c_{2}, g_{1} & c_{2}, g_{2} \\ 0.254, 0.206, 0.290, 0.250 \end{pmatrix}$
$M_{35} = \begin{pmatrix} f_{1}, g_{1}, f_{1}, g_{2}, f_{2}, g_{1}, f_{2}, g_{2} \\ 0.14, 0.12, 0.40, 0.33 \end{pmatrix}$
$M_{53} = \begin{pmatrix} f_{1}, g_{1}, f_{1}, g_{2}, f_{2}, g_{1}, f_{2}, g_{2} \\ 1, 1, 1, 1 \end{pmatrix}$
$M_{31} = \begin{pmatrix} c_1, g_1, c_1, g_2, c_2, g_1, c_2, g_2 \\ 1, 1, 1, 1, 1 \end{pmatrix}$
$M_{12} = \begin{pmatrix} b_1, c_1 & b_1, c_2 & b_2, c_1 & b_2, c_2 \\ 1 & 1 & 1 & 1 & 1 \end{pmatrix}$
$M_{14} = \begin{pmatrix} b_1 \\ 0.16, 0.84 \end{pmatrix}$

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Example: Step 3: Initialization Complete



Ψ_1					P
		0.4	g_1	0.190	0.0122
	Ca	e_1	g_2	0.010	0.0006
	c_1	60	g_1	0.320	0.0205
b_1		e_2	g_2	0.480	0.0307
o_1		e_1	g_1	0.380	0.0365
	c_2		g_2	0.020	0.0019
	C2	Po	g_1	0.240	0.0230
		e_2	g_2	0.360	0.0346
		01	g_1	0.210	0.0832
	C1	e_1	g_2	0.090	0.0356
	c_1	00	g_1	0.350	0.1386
b_2		e_2	g_2	0.350	0.1386
02		01	g_1	0.070	0.0311
	Co	e_1	g_2	0.030	0.0133
	c_2	60	g_1	0.450	0.1998
		e_2	g_2	0.450	0.1998



BC

Ψ_5				P
	a.	h_1	0.2	0.0283
$ f_1 $	g_1	h_2	0.8	0.1133
J1	g_2	h_1	0.5	0.0602
		h_2	0.5	0.0602
	g_1	h_1	0.4	0.1613
f_2		h_2	0.6	0.2419
	a ₂	h_1	0.7	0.2344
	g_2	h_2	0.3	0.1004

Ψ_4			P
b_1	d_1	0.4	0.0640
o_1	d_2	0.6	0.0960
h-	d_1	0.7	0.5880
b_2	d_2	0.3	0.2520
			P

Ψ_3		P		
	f_1	g_1	0.1	0.0254
c_1	$\int \int 1$	g_2	0.1	0.0206
	f_2	g_1	0.9	0.2290
		g_2	0.9	0.1850
	f_1 f_2	g_1	0.4	0.1162
c_2		g_2	0.4	0.0998
		g_1	0.6	0.1742
		g_2	0.6	0.1498

$M_{21} =$	$\begin{pmatrix} b_1, c_1 & b_1, c_2 & b_2, c_1 & b_2, c_2 \\ 0.06, 0.10, 0.40, 0.44 \end{pmatrix}$
	b_1 b_2

$$M_{41} = \begin{pmatrix} b_1 & b_2 \\ 1 & 1 \end{pmatrix}$$

$$M_{13} = \begin{pmatrix} c_{1}, g_{1} & c_{1}, g_{2} & c_{2}, g_{1} & c_{2}, g_{2} \\ 0.254, 0.206, 0.290, 0.250 \end{pmatrix}$$

$$M_{35} = \begin{pmatrix} f_{1}, g_{1} & f_{1}, g_{2} & f_{2}, g_{1} & f_{2}, g_{2} \\ 0.14, & 0.12, & 0.40, & 0.33 \end{pmatrix}$$

$$M_{53} = \begin{pmatrix} f_{1}, g_{1}, f_{1}, g_{2}, f_{2}, g_{1}, f_{2}, g_{2} \\ 1, 1, 1, 1 \end{pmatrix}$$

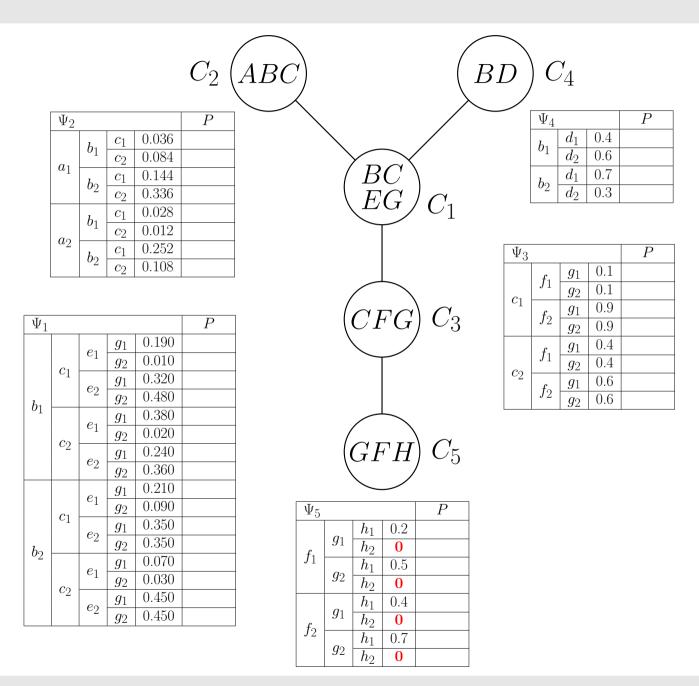
$$M_{31} = \begin{pmatrix} c_{1}, g_{1}, c_{1}, g_{2}, c_{2}, g_{1}, c_{2}, g_{2} \\ 1, 1, 1, 1 \end{pmatrix}$$

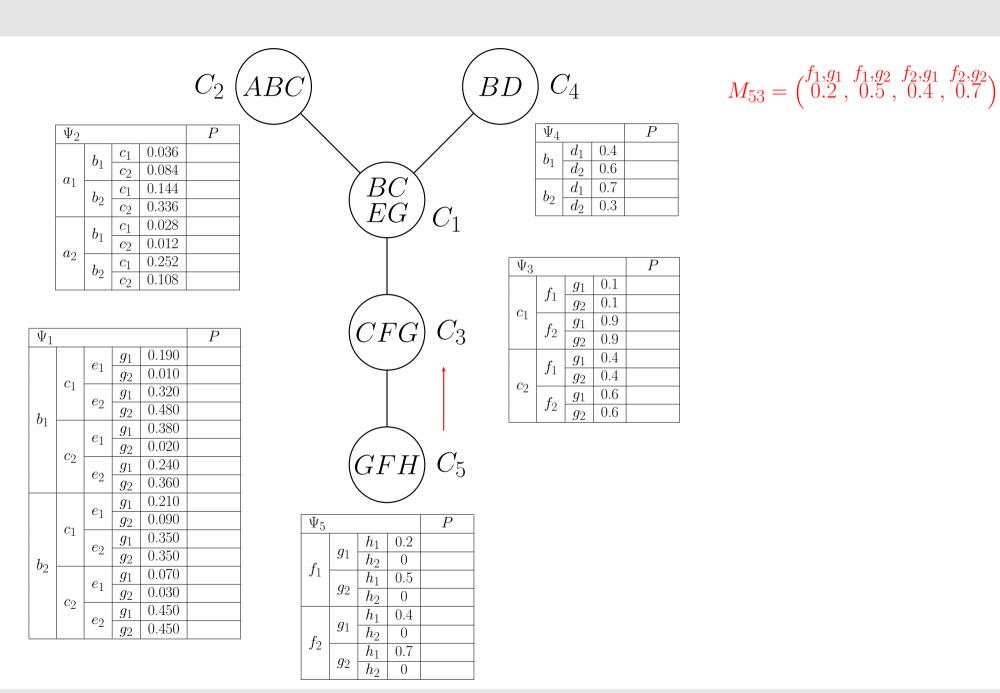
$$M_{12} = \begin{pmatrix} b_1, c_1 & b_1, c_2 & b_2, c_1 & b_2, c_2 \\ 1 & 1 & 1 & 1 & 1 \end{pmatrix}$$

$$M_{14} = \left(0.16, 0.84\right)$$

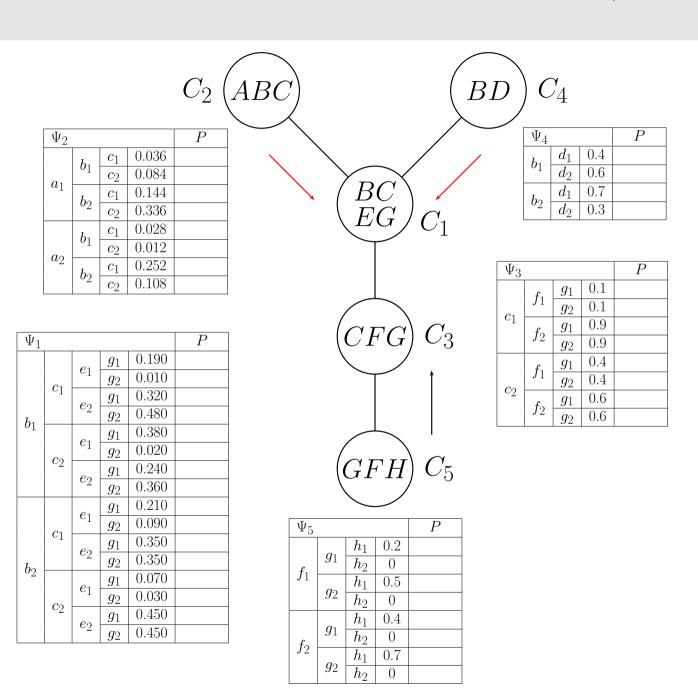
P	A	B	C	D	E	F	G	H
•1	0.6000	0.1600	0.4600	0.6520	0.2144	0.2620	0.5448	0.4842
•2	0.4000	0.8400	0.4500	0.3480	0.7856	0.7380	0.4552	0.5158

Example: Step 4: Evidence $H = h_1$ (Altering Potentials)

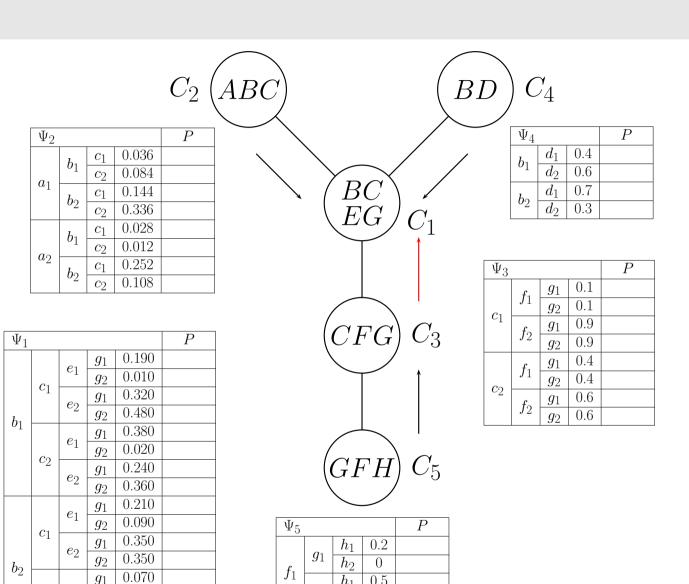




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$M_{53} = \begin{pmatrix} f_{1}, g_{1}, f_{1}, g_{2}, f_{2}, g_{1}, f_{2}, g_{2} \\ 0.2, 0.5, 0.4, 0.7 \end{pmatrix}$
$M_{21} = \begin{pmatrix} b_1, c_1 & b_1, c_2 & b_2, c_1 & b_2, c_2 \\ 0.06, 0.10, 0.40, 0.40 \end{pmatrix}$
$M_{41} = \begin{pmatrix} b_1 & b_2 \\ 1 & 1 \end{pmatrix}$



 h_1

 h_2

 h_1

 h_2

 h_1 h_2 0.5

0

0.4

0 0.7

$M_{53} = \begin{pmatrix} f_{1}, g_{1}, f_{1}, g_{2}, f_{2}, g_{1}, f_{2}, g_{2} \\ 0.2, 0.5, 0.4, 0.7 \end{pmatrix}$
$M_{21} = \begin{pmatrix} b_1, c_1 & b_1, c_2 & b_2, c_1 & b_2, c_2 \\ 0.06, 0.10, 0.40, 0.40 \end{pmatrix}$
$M_{41} = \begin{pmatrix} b_1 & b_2 \\ 1 & 1 \end{pmatrix}$
$M_{31} = \begin{pmatrix} c_1, g_1 & c_1, g_2 & c_2, g_1 & c_2, g_2 \\ 0.38, 0.68, 0.32, 0.62 \end{pmatrix}$

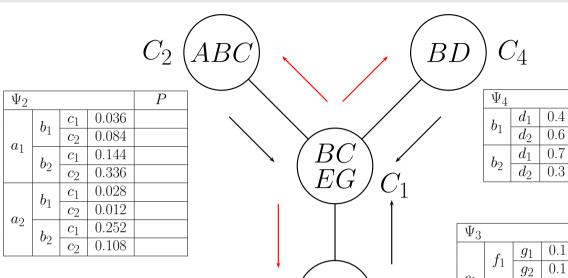
 g_1

0.030

0.450

0.450

 e_1



Ψ_1					P
		01	g_1	0.190	
	c_1	e_1	g_2	0.010	
		e_2	g_1	0.320	
b_1		C2	g_2	0.480	
		$ e_1 $	g_1	0.380	
	c_2		g_2	0.020	
	C2	e_2	g_1	0.240	
			g_2	0.360	
		e_1 e_2	g_1	0.210	
	c_1		g_2	0.090	
			g_1	0.350	
b_2			g_2	0.350	
		P1	g_1	0.070	
	c_2	e_1	g_2	0.030	
		e_2	g_1	0.450	
			g_2	0.450	

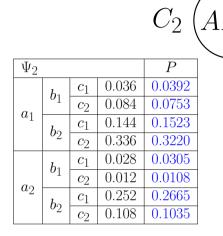
Ψ_5				P				
	a.	h_1	0.2					
f_1	g_1	h_2	0					
$\int \int 1$	g_2	h_1	0.5					
		h_2	0					
	Q,	h_1	0.4					
$ f_2 $	g_1	h_2	0					
J^2	a ₀	h_1	0.7					
	g_2	h_2	0					

Ψ_3				P
	f_1	g_1	0.1	
c_1		g_2	0.1	
	f_2	g_1	0.9	
		g_2	0.9	
Ca	f_1	g_1	0.4	
		g_2	0.4	
c_2	f_{α}	g_1	0.6	
	$ f_2 $	an	0.6	

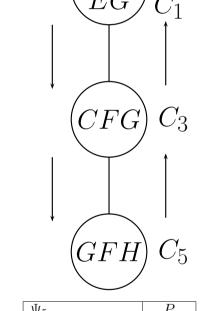
$M_{53} = \begin{pmatrix} f_{1}, g_{1}, f_{1}, g_{2}, f_{2}, g_{1}, f_{2}, g_{2} \\ 0.2, 0.5, 0.4, 0.7 \end{pmatrix}$
$M_{21} = \begin{pmatrix} b_1, c_1 & b_1, c_2 & b_2, c_1 & b_2, c_2 \\ 0.06, 0.10, 0.40, 0.40 \end{pmatrix}$
$M_{41} = \begin{pmatrix} b_1 & b_2 \\ 1 & 1 \end{pmatrix}$
$M_{31} = \begin{pmatrix} c_{1}, g_{1} & c_{1}, g_{2} & c_{2}, g_{1} & c_{2}, g_{2} \\ 0.38, 0.68, 0.32, 0.62 \end{pmatrix}$
$M_{12} = \begin{pmatrix} b_1, c_1 & b_1, c_2 & b_2, c_1 & b_2, c_2 \\ 0.527, 0.434, 0.512, 0.464 \end{pmatrix}$
$M_{14} = \left(0.075, 0.409\right)$
$M_{13} = \begin{pmatrix} c_{1}, g_{1} & c_{1}, g_{2} & c_{2}, g_{1} & c_{2}, g_{2} \\ 0.254, 0.206, 0.290, 0.250 \end{pmatrix}$
$M_{35} = \begin{pmatrix} f_{1}, g_{1} & f_{1}, g_{2} & f_{2}, g_{1} & f_{2}, g_{2} \\ 0.14 & 0.12 & 0.40 & 0.33 \end{pmatrix}$

Example: Step 4: Evidence $H = h_1$ Incorporated

BD



Ψ_1					P
		_	g_1	0.190	0.0095
	Ca	e_1	g_2	0.010	0.0009
	c_1	e_2	g_1	0.320	0.0161
b_1		C2	g_2	0.480	0.0431
01		e_1	g_1	0.380	0.0241
	c_2		g_2	0.020	0.0025
	<i>O</i> 2	e_2	g_1	0.240	0.0152
			g_2	0.360	0.0443
		e_1 e_2	g_1	0.210	0.0653
	c_1		g_2	0.090	0.0501
			g_1	0.350	0.1088
b_2			g_2	0.350	0.1947
02		e_1	g_1	0.070	0.0205
	c_2		g_2	0.030	0.0171
		e_2	g_1	0.450	0.1321
			g_2	0.450	0.2559



BC

Ψ_5				P
	g_1	h_1	0.2	0.0585
f_1		h_2	0	0
	g_2	h_1	0.5	0.1243
		h_2	0	0
f_2	g_1	h_1	0.4	0.3331
		h_2	0	0
J2	g_2	h_1	0.7	0.4841
		h_2	0	0

Ψ_4			P
b_1	d_1	0.4	0.0623
o_1	d_2	0.6	0.0934
h-	d_1	0.7	0.5910
b_2	d_2	0.3	0.2533

Ψ_3		P		
c_1	f_1	g_1	0.1	0.0105
		g_2	0.1	0.0212
	f_2	g_1	0.9	0.1892
		g_2	0.9	0.2675
- Ca	f_1	g_1	0.4	0.0480
		g_2	0.4	0.1031
c_2	f_2	g_1	0.6	0.1440
		g_2	0.6	0.2165

$$M_{53} = \begin{pmatrix} f_{1}, g_{1} & f_{1}, g_{2} & f_{2}, g_{1} & f_{2}, g_{2} \\ 0.2 & 0.5 & 0.4 & 0.7 \end{pmatrix}$$

$$M_{21} = \begin{pmatrix} b_1, c_1 & b_1, c_2 & b_2, c_1 & b_2, c_2 \\ 0.06, 0.10, 0.40, 0.40 \end{pmatrix}$$

$$M_{41} = \begin{pmatrix} b_1 & b_2 \\ 1 & 1 \end{pmatrix}$$

$$M_{31} = \begin{pmatrix} c_{1}, g_{1} & c_{1}, g_{2} & c_{2}, g_{1} & c_{2}, g_{2} \\ 0.38, 0.68, 0.32, 0.62 \end{pmatrix}$$

$$M_{12} = \begin{pmatrix} b_1, c_1 & b_1, c_2 & b_2, c_1 & b_2, c_2 \\ 0.527, 0.434, 0.512, 0.464 \end{pmatrix}$$

$$M_{14} = \left(0.075, 0.409\right)$$

$$M_{13} = \begin{pmatrix} c_{1}, g_{1} & c_{1}, g_{2} & c_{2}, g_{1} & c_{2}, g_{2} \\ 0.254, 0.206, 0.290, 0.250 \end{pmatrix}$$

$$M_{35} = \begin{pmatrix} f_{1}, g_{1} & f_{1}, g_{2} & f_{2}, g_{1} & f_{2}, g_{2} \\ 0.14 & 0.12 & 0.40 & 0.33 \end{pmatrix}$$

P	A	B	C	D	E	F	G	H
•1	0.5888	0.1557	0.4884	0.6533	0.1899	0.1828	0.3916	1.0000
•2	0.4112	0.8443	0.5116	0.3467	0.8101	0.8172	0.6084	0.0000

Summary

There are several exact inference methods such as variable elimination, clique tree propagation or recursive conditioning. These algorithms have complexity that is exponential with networks tree width. Exact inference is NP-hard.

In very large applications it is necessary to introduce topological structural constraints or restrictions on conditional probabilities, i.e. bounded variance algorithms.